

User Manual

GO-5100MP-USB

5.1M CMOS Digital Progressive Scan Polarized Camera Document Version: 1.0 GO-5100MP-USB_Ver.1.0_Nov.2018

Thank you for purchasing this product.



Be sure to read this manual before use.

This manual includes important safety precautions and instructions on how to operate the unit. Be sure to read this manual to ensure proper operation.

The contents of this manual are subject to change without notice for the purpose of improvement.

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Notice

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Warranty

For information about the warranty, please contact your factory representative.

Certifications

CE compliance

As defined by the Directive 2004/108/EC of the European Parliament and of the Council, EMC (Electromagnetic compatibility), JAI Ltd., Japan declares that GO-5100MP-USB complies with the following provisions applying to its standards.

EN 61000-6-3 (Generic emission standard part 1)

EN 61000-6-2 (Generic immunity standard part 1)

FCC

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Warning

Changes or modifications to this unit not expressly approved by the party responsible for FCC compliance could void the user's authority to operate the equipment.

Supplement

The following statement is related to the regulation on "Measures for the Administration of the control of Pollution by Electronic Information Products ", known as "China RoHS". The table shows contained Hazardous Substances in this camera.



mark shows that the environment-friendly use period of contained Hazardous Substances is 15 years.

重要注意事项

有毒,有害物质或元素名称及含量表

根据中华人民共和国信息产业部『电子信息产品污染控制管理办法』,本产品《有毒,有害物质或元素名称及含量表》如下.

		有毒有害物质或元素									
部件名称	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr (VI))	多溴联苯 (PPB)	多溴二苯醚 (PBDE)					
棱镜	×	0	0	0	0	0					
光学滤镜	×	0	×	0	0	0					
连接插头	×	0	0	0	0	0					
电路板	×	0	0	0	0	0					

- 〇:表示该有毒有害物质在该部件所有均质材料中的含量均在SJ/T11363-2006规定的限量要求以下。
- ×:表示该有毒有害物质至少在该部件的某一均质材料中的含量超出SJ/T11363-2006规定的限量要求。
- (企业可在此处、根据实际情况对上表中打"×"的技术原因进行进一步说明。)



环保使用期限

电子信息产品中含有的有毒有害物质或元素在正常使用的条件下不会发生外 泄或突变、电子信息产品用户使用该电子信息产品不会对环境造成严重污染 或对基人身、财产造成严重损害的期限。

数字「15」为期限15年。

Usage Precautions

Notes on cable configurations

The presence of lighting equipment and television receivers nearby may result in video noise. In such cases, change the cable configurations or placement.

Notes on attaching the lens

Avoiding dust particles

When attaching the lens to the camera, stray dust and other particles may adhere to the sensor surface and rear surface of the lens. Be careful of the following when attaching the lens.

- Work in a clean environment.
- Do not remove the caps from the camera and lens until immediately before you attach the lens.
- To prevent dust from adhering to surfaces, point the camera and lens downward and do not allow the lens surface to come into contact with your hands or other objects.
- Always use a blower brush to remove any dust that adheres.

 Never use your hands or cloth, blow with your mouth, or use other methods to remove dust.

Phenomena specific to CMOS image sensors

The following phenomena are known to occur on cameras equipped with CMOS image sensors. These do not indicate malfunctions.

- Aliasing When shooting straight lines, stripes, and similar patterns, vertical aliasing
- (zigzag distortion) may appear on the monitor.Blooming

When strong light enters the camera, some pixels on the CMOS image sensor may receive much more light than they are designed to hold, causing the accumulated signal charge to overflow into surrounding pixels. This "blooming" phenomenon can be seen in the image, but does not affect the operation of the camera.

- Fixed pattern noise
 When shooting dark objects in high-temperature conditions, fixed pattern noise may occur throughout the entire video monitor screen.
- Defective pixels
 Defective pixels (white and black pixels) of the CMOS image sensor are minimized at the factory according to shipping standards. However, as this phenomenon can be affected by the ambient temperature, camera settings (e.g., high sensitivity and long exposure), and other factors, be sure to operate within the camera's specified operating environment.

Notes on exportation

When exporting this product, please follow the export regulations of your country or region.

Features

The GO-5100MP-USB is a machine vision polarization camera incorporating a monochrome CMOS image sensor with a 2/3-inch global shutter and a four-directional polarization square pixel array that offers 5.1 effective megapixels (2464 \times 2056). The unit is compact and lightweight in design and is equipped with a USB 3.0 interface.

Image sensor with four-directional polarization Polarizers are provided for individual pixels to capture polarization.

90	45	90	45	90	45
135	0	135	0	135	0
90	45	90	45	90	45
135	0	135	0	135	0
90	45	90	45	90	45
135	0	135	0	135	0

The numbers in the figure on the left indicate the polarizer angles.

Four polarizer angles are available: 0°, 45°, 90°, and 135°. Various polarization processing is performed on the four pixels enclosed in the red frame as a block.

Also, various functions considered necessary for machine vision are provided.

The unit is equipped with pre-processing circuits for shading correction and blemish correction in addition to external trigger, exposure setting, and image level control.

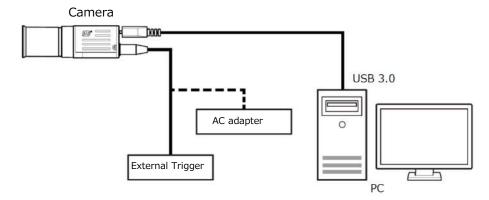
Feature overview

- Compliance with USB3 Vision and GenICam standards
- 2/3-inch global shutter and a four-directional polarization square pixel array that offers 5.1 effective megapixels CMOS sensor
- Lens mount: C-mount (flange back: 17.526 mm)
- Pixel size : 3.45 um × 3.45 um
- Effective pixels 2464(H) × 2056(V)
- Up to 74 fps at full resolution
- Various Video Output modes

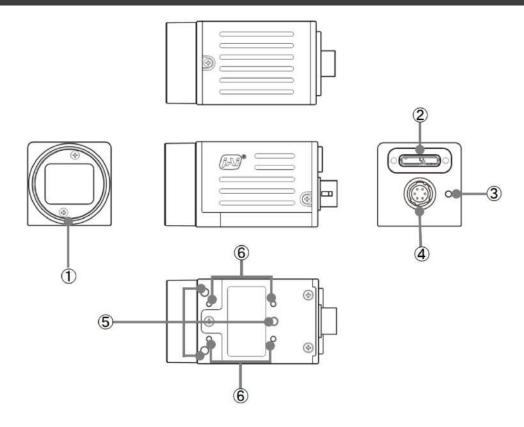
Raw Image, Four polarizer, Four functions, Color on average image and Color on gray image.

- Internal test signal for settings configuration
- eBUS SDK for JAI that supports Windows 7, 8, 10

Connection example:



Parts Identification



1 Lens mount (C-mount)

Mount a C-mount lens, microscope adapter, etc. here.

❖ Before mounting a lens, be sure to refer to "Step 2:Connecting Devices" and confirm the precautions for attaching a lens and the supported lens types.

2 USB 3.0 connector

Use a USB 3.0 compatible cable to connect this to a USB port on the computer.

3 POWER/TRIG LED

Indicates the power and trigger input status.

LED status and camera status

LED	Light	Status
POWER/	(Lit amber)	Camera initializing.
TRIG LED	(Lit green)	Camera in operation.
	* (Blinking green)	During operation in trigger mode, trigger signals are being input. The blinking interval is not related to the actual input interval of the external trigger.

4 DC IN/TRIG connector (6-pin round)

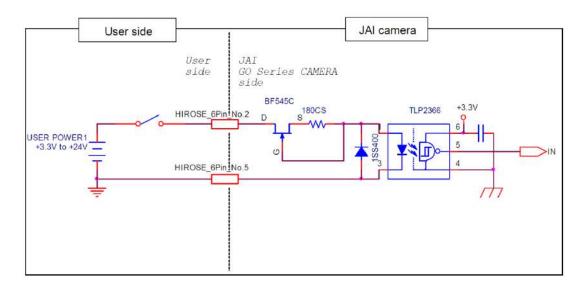
Connect the cable for a power supply (optional) or for DC IN / trigger IN here.



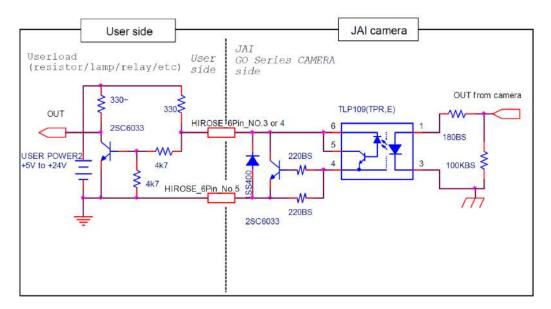
HR10A-7R-6PB (73) (Hirose Electric or equivalent)

Pin No.	Input/Output	Signal	Description
1	Power In	DC In	DC 12 V \sim 24 V \pm 10%
2	In	Opto In 1	GPIO 5
3	Out	Opto In 1	GPIO 1
4	Out	Opto In 2 +	GPIO 2
5		Opto Common	
6		GND	

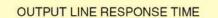
Recommended external input circuit diagram (reference example)

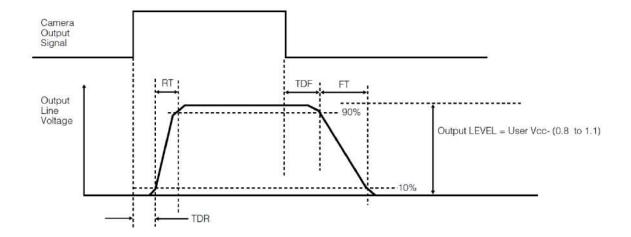


Recommended external output circuit diagram (reference example) Standard circuit diagram example



Characteristics of the recommended circuits for Opto OUT





5 Camera locking screw holes (M3, 3mm depth)

Use these holes when attaching an MP-43 tripod adapter plate (optional) or mounting the camera directly to a wall or other structural system.

6 Camera locking screw holes (M2, 3mm depth)

Use these holes when mounting the camera directly to a wall or other structural system.

Preparation

Preparation Process

Step 1	Installing the Software (first time only) Install the software for configuring and controlling the camera (eBUS SDK for JAI) on the computer.
	Install the software for configuring and controlling the carriera (eBOS SDK for SAI) on the computer.
Step 2	Connecting Devices
-	Connect the lens, USB cable, AC adapter, computer, and other devices.
	₩
Step 3	Verifying Camera Operation
	Verify whether the camera is turned on and ready for use.
	<u> </u>
Step 4	Verifying the Connection between the Camera and PC
otep .	Verify whether the camera is properly recognized via eBUS Player for JAI.
	•
Step 5	Changing the Camera Settings
Step 3	Refer to the procedure for changing the output format setting as an example, and change various settings as necessary.
•	•
Step 6	Adjusting the Image Quality
	Refer to the procedures for adjusting the gain, white balance, and black level as examples, and adjust the image quality.
	•
Step 7	Saving the Settings
otep /	Save the current setting configurations in user memory.

Step 1: Installing the Software (first time only)

When using the camera for the first time, install the software for configuring and controlling the camera (eBUS SDK for JAI) on the computer.

❖ When you install eBUS SDK for JAI, eBUS SDK for JAI player will also be installed.

1 Download the eBUS SDK for JAI from the JAI website. URL https://www.jai.com/support-software/jai-software

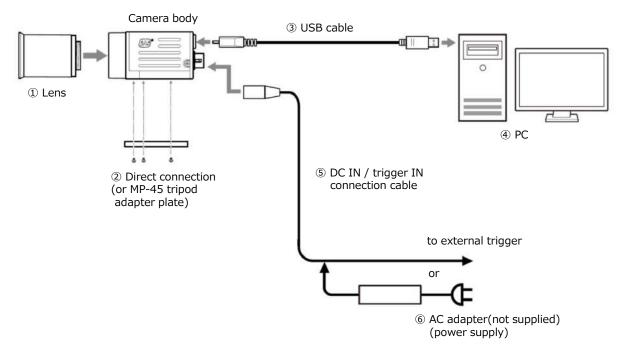
1 Install eBUS SDK for JAI on the computer.

Caution

eBUS SDK for JAI was released in April 2018 and is the latest software for setting and controlling JAI cameras.

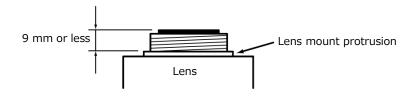
When JAI SDK and eBUS SDK for JAI are installed on the same machine, conflicts can occur. Therefore, JAI strongly recommends that JAI SDK is uninstalled before installing eBUS SDK for JAI.

Step 2: Connecting Devices



1 Lens

• C-mount lenses with lens mount protrusions of 9 mm or less can be attached.



• The diagonal of the camera's CMOS image sensor is 11 mm, the size of standard 2/3-inch lenses.

To prevent vignetting and to obtain the optimal resolution, use a lens that will cover the 11 mm diagonal. Some lens manufacturers offer lenses with an 11 mm format. If not, a 2/3-inch lens is recommended.

Caution -

- The maximum performance of the camera may not be realized depending on the lens.
- Attaching a lens with a mount protrusion of 9 mm or longer may damage the lens or camera.

Note

The following formula can be used to estimate the focal length.

Focal length = WD / (1 + W/w)

WD: Working distance (distance between lens and object)

W: Width of object

w : Width of sensor (8.5 mm on this camera)

2 Direct connection (or MP-43 tripod adapter plate)

When mounting the camera directly to a wall or other device, use screws that match the camera locking screw holes on the camera (M3, depth: 3 mm). Use the supplied screws to attach the tripod adapter plate.

Caution =

For heavy lenses, be sure to support the lens itself. Do not use configurations in which its weight is supported by the camera.

3 USB cable

Connect a USB cable to the USB 3.0 connector.

Caution

The camera is equipped with a USB 3.0 compatible Micro B connector. Although this connector includes USB 2.0 connectors, the camera does not support use of USB 2.0.

4 Computer

Use a computer that meets the following requirements.

Operating system (OS):

Microsoft Windows 7/8/10 32-bit/64-bit edition

CPU: Intel Core i3 or higher

Memory:

Windows 7/8/10 32-bit edition: DDR3, 4 GB or higher Windows 7/8/10 64-bit edition: DDR3, 8 GB or higher

Graphics card: PCI-Express 3.0 or higher **Interface:** USB 3.0 compatible connector

5 DC IN / trigger IN connection cable

6 AC adapter (power supply) (if necessary)

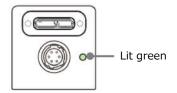
Connect the AC adapter and the round connector of the connection cable to the DC IN / trigger IN connector on the camera.

Step 3: Verifying Camera Operation

When power is supplied to the camera while the necessary equipment is connected, the POWER/TRIG LED at the rear of the camera lights amber, and initialization of the camera starts. When initialization is complete, the POWER/TRIG LED lights green.

Verify whether power is being supplied to the camera by checking the rear LED.

When properly turned on



* For details on how to read the LEDs, see "LED status and camera status" in the "Parts Identification" section.

Step 4: Verifying the Connection between the Camera and PC

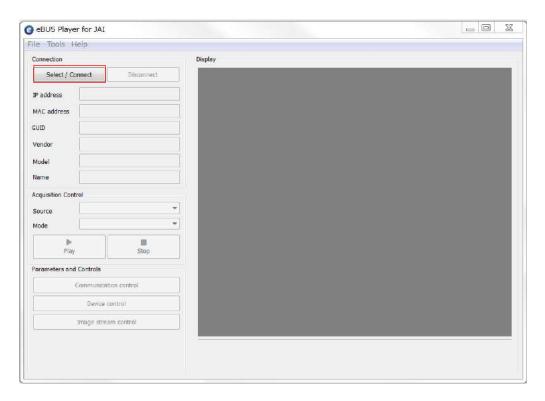
Verify whether the camera is properly recognized via eBUS Player for JAI.

Connecting the Camera to eBUS Player for JAI.

1 Startup eBUS Player for JAI

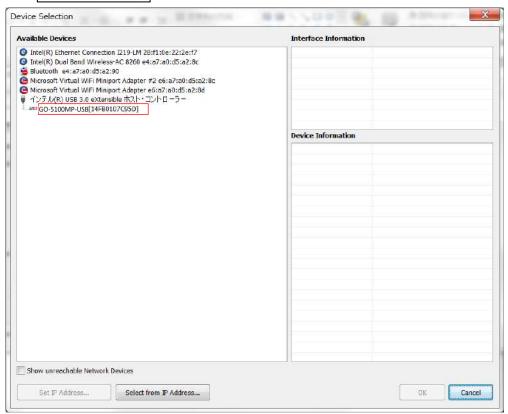


eBUS Player for JAI startup screen appears.



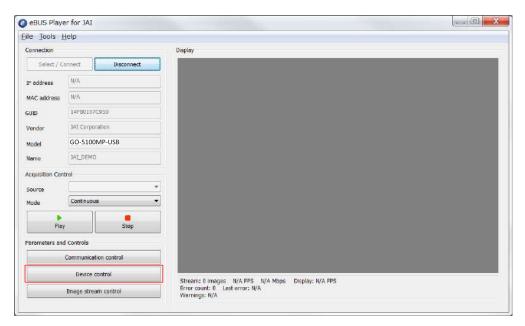
2 Select the camera you want to configure.

Push Select / Connect button



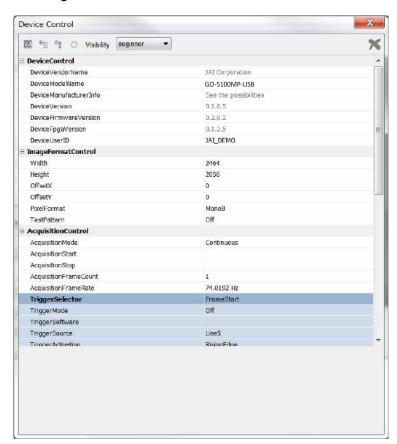
The connected camera is listed. Please select one camera.

? Check that the settings of the selected camera are displayed.



Push the Device control button.

The screen shown below will be displayed. In this window you can adjust various settings of the camera.



This completes the procedure for verifying whether the camera is properly recognized and whether control and settings configuration are possible.

Step 5: Changing the Camera Settings

This section explains how to change settings by describing the procedure for changing the output format as an example.

Configuring the Output Format

Configure the size, position, and pixel format of the images to be acquired. The factory settings are as follows. Change the settings as necessary.

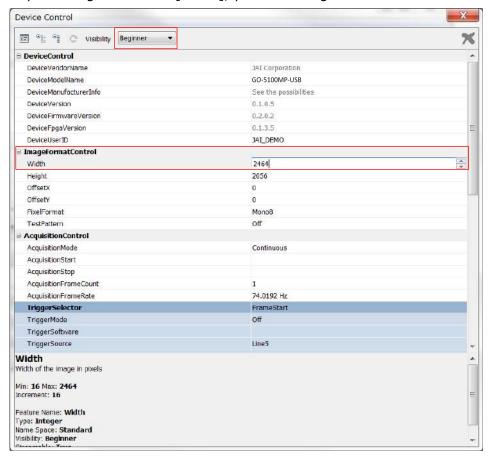
Factory default values

It	Item			
ImageFormatControl	Width	2464		
	Height	2056		
	OffsetX (horizontal position)	0		
	OffsetY (vertical position)	0		
	PixelFormat	Mono8		

^{*} You can specify the image acquisition area. For details, see "ROI (Regional Scanning Function)".

1 Configuring the [Width] of [ImageFormatControl]

By selecting the item of [Width], you can change the value as shown below.



Note

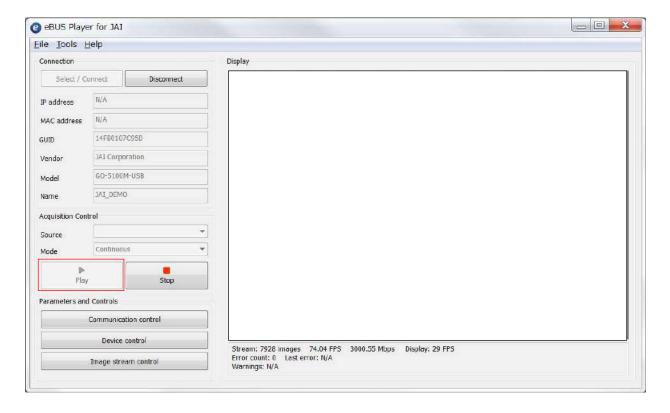
Depending on the setting item, you need to change visibility. Please switch visibility (Beginner / Expert / Guru) as necessary.

Step 6: Adjusting the Image Quality

Display the camera image and adjust the image quality.

Displaying the Image

Display the image captured by the camera. When you push [Play] button, the camera image appears in right area.



Adjusting the Gain

Adjust the image quality using the gain function.

To adjust the image quality

The Visibility must be changed from [Beginner] to [Guru].

Adjust the sensitivity via the analog gain (i.e., master gain). For details on gain control, see "Gain Control" in the "Main Functions" section.

■ Manual adjustment

1 Expand [AnalogControl], and set [GainAuto] to [Off].

([Off] is default setting.)

7 Configure the gain.

- Expand [AnalogControl], and select the gain you want to configure in [GainSelector]. [AnalogAll] (master gain) can be configured.
- 2 Configure the gain value in [Gain].
 - [AnalogAll] (master gain) can be set to a value from x1 to x16 the analog gain value. The resolution is set in x0.1 steps. Values are configured by multipliers.

Adjusting the Black Level

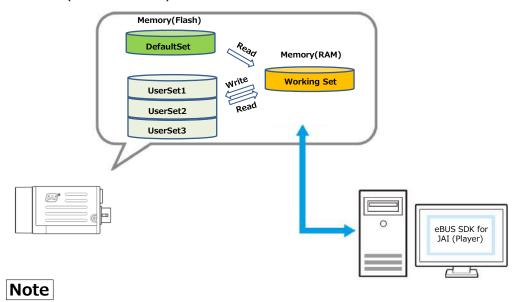
1 Expand [AnalogControl], and select the black level you want to configure in [BlackLevelSelector].

[DigitalAII] (master black) can be configured.

2 Specify the adjustment value in [BlackLevel].

Step 7: Saving the Settings

The setting values configured in the player (eBUS SDK for JAI) will be deleted when the camera is turned off. By saving current setting values to user memory, you can load and recall them whenever necessary. You can save up to three sets of user settings in the camera. (User Set1 to 3)



Changes to settings are not saved to the computer (eBUS SDK for JAI).

- To save user settings
 - **1** Stop image acquisition.
 - **2** Expand [UserSetControl], and select the save destination ([UserSet1] to [UserSet3]) in [UserSetSelector].

Note

The factory default setting values are stored in [Default] and cannot be overwritten.

Caution =

Settings can only be saved when image acquisition on the camera is stopped.

3 Select [UserSetSave], and click [Execute 'UserSetSave' Command].

The current setting values are saved as user settings.

- To load user settings
 - **1** Stop image acquisition.

 User settings can only be loaded when image capture on the camera is stopped.
 - **2** Select the settings to load (UserSet1 to UserSet3) in [UserSetSelector].
 - **3** Select [UserSetLoad], and click [Execute 'UserSetLoad' Command].

The selected user settings are loaded.

Main Functions

Basic Function Matrix

The combinations of settings for the basic functions that can be used together are as follows.

E X	Fra	E XD	ROI	Gai	Sequ	encer
ExposureMode	FrameStartTrigger	ExposureTime	I	GainAuto	TriggerSequencerMode	CommandSequencerMode
Off	Off	×	0	\circ	×	×
Timed	Off	0	0	0	×	0
Timed(EPS)	On	0	0	0	0	0
TriggerWidth	On	×	0	0	×	×

GPIO (Digital Input/Output Settings)

The camera is equipped with GPIO (general-purpose input/output) functions for generating and using combinations of triggers and other necessary signals within the camera and of signals output from the camera to the system such as those used for lighting equipment control.

Valid Input/Output Combinations

The following signals can be used as sources for each output destination (Trigger Selector, Line Selector, Pulse Generator Selector).

You can also connect two different sources to NAND paths in the GPIO and reuse the signal generated there as a source for a different selector.

The combinations of source signals and output destinations are indicated in the following.

/	Selector					Out	put de	estina	tion		
	(Cross point switch output)		Trigger Selector Line Selector							Pulse Generator Selector	
(Cr	urce signal oss point itch input)	Acquisition Start	Acquisition Stop	Frame Start	Transfer Start	Line2 OPT Out 1	Line3 OPT Out 2	Time Stamp Reset	Nand Gate 0 In	Nand Gate 1 In	Pulse Generator 0
	LOW	0	0	0	0	0	0	0	0	0	0
	HIGH	0	0	0	0	0	0	0	0	0	0
	Line5 - Optical In 1	0	0	0	0	0	0	0	0	0	0
	NAND 0 Out	0	0	0	0	0	0	0	×	0	0
Sig	NAND 1 Out	0	0	0	0	0	0	0	0	×	0
Signals to	Pulse Generator 0	0	0	0	0	0	0	0	0	0	×
ਰ	User Output 0	0	0	0	0	0	0	0	0	0	0
esu	User Output 1	0	0	0	0	0	0	0	0	0	0
as	Software Trigger	0	0	0	0	×	×	×	×	×	×
2	FVAL	×	×	×	×	0	0	0	0	0	0
as output	LVAL	×	×	×	×	×	×	0	0	0	0
	Acquisition Trigger Wait	×	×	×	×	0	0	0	O	0	0
	Frame Trigger Wait	×	×	×	×	0	0	0	0	0	0
	Frame Active	×	×	×	×	0	0	0	0	0	0
	Exposure Active	×	×	×	×	0	0	0	0	0	0
		3	Frigger	Sourc	е		Lir	ne Sou	rce		Pulse Generator Clear Source
						00-	Us	se			

: Indicates default values for each selector.

Camera Output Formats

The GO-5100MP-USB supports the following output formats.

PixelFormat

Mono8, Mono10, Mono10packed

- *1) Mono12, Mono12Packed
- *2) BayerRG8, BayerRG10, BayerRG10Packed
- *1) When VideoProcessBypassMode is enabled, PixelFormat can be set to Mono12 or Mono12Packed. In this case, the image output mode of the camera will be fixed to the RawImage mode. For details, see "12-bit Output" section.
- *2) PixelFormat is switched to BayerRG8, BayerRG10, or BayerRG10Packed automatically depending on the output mode setting (PolarizeImageSelector) of the camera. For details, see the "Camera Image Output Modes" section.

Camera Image Output Modes

The GO-5100MP-USB has five output modes.

First, we will explain about the monochrome CMOS image sensor with a four-directional polarization square pixel array that is incorporated in this camera.

A polarizer with one of the four angles of 0°, 45°, 90°, and 135° is provided for each pixel.

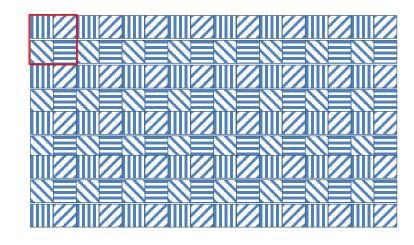
90	45	90	45	90	45
135	0	135	0	135	0
90	45	90	45	90	45
135	0	135	0	135	0
90	45	90	45	90	45
135	0	135	0	135	0

The numbers in the figure on the left indicate the polarizer angles.

Four polarizer angles are available: 0°, 45°, 90°, and 135°. Various polarization processing is performed on the four pixels enclosed in the red frame as a block.

The number of effective pixels is 2464 x 2056, and polarizers angled at 90° and 45° are provided alternately for each pixel on the first line. Polarizers angled at 135° and 0° are provided alternately for each pixel on the second line.

2464 pixels

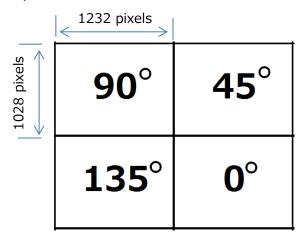


1. RawImage mode

The data output from the image sensor is output as is from the camera. As shown in the figure above, the data of the pixels where there are polarizers angled at 90° and 45° is output as the first line, and the data of the pixels where there are polarizers angled at 135° and 0° is output as the second line.

2. FourPolarizeElement mode

The data is output arranged as a screen divided into four (pixels of the polarizers angled at 45° at the top right, pixels of the polarizers angled at 90° at the top left, pixels of the polarizers angled at 0° at the bottom right, and pixels of the polarizers angled at 135° at the bottom left).



3. FourFunctions mode

This mode allows you to set each quadrant of the screen to one of five available functions. The five selectable functions are:

PolarizeAngle (polarization angle), PolarizeRatio (polarization ratio), DiffusedLight (diffused light), PolarizedLight (polarized light), and AverageLight (average brightness)

The follow example shows the settings that would be used to configure the output into four functions arranged as shown in the screen diagram below.

PolarizeAngle	PolarizeRatio
DiffusedLight	PolarizedLight

Setting itemSetting valuePolarizeImageSelector:FourFunctionsPanel1selector:PolarizeAnglePanel2selector:PolarizeRatioPanel3selector:DiffusedLightPanel4selector:AverageLight

*) The same function can be output in multiple quadrants.

Polarization angle:

The polarization angle producing the greatest luminance for a given pixel block. Intensity values assigned to pixels represent angles from 0 to 180°.

8-bit output: 00000000 to 10110100 10-bit output: 0000000000 to 1110000100

Polarization ratio:

The proportion of polarized light (at the angle described above) contained within the total light falling on a pixel block. Intensity values represent proportions of polarized light from 0 to 100%.

8-bit output: 00000000 to 11111111 10-bit output: 000000000 to 111111111

Diffused light:

The intensity of light falling on a pixel block when some or all of the polarized light is excluded. The ReflectionAdjust control determines how much of the polarized component is removed. The higher the ReflectionAdjust setting, the more polarized light is removed. Set to maximum to display only the diffused component.

Polarized light:

The intensity of the polarized light that is falling on a pixel block after the diffused light has been excluded.

Average light:

The brightness of a pixel block when the polarized component and the diffused component are averaged.

Two additional output modes are available to users. These are not selectable in the FourFunctions mode. Instead, they produce a single image that combines information from the functions above with the main image being captured.

4. ColorOnPicture mode

This mode provides a pseudo-color overlay representing polarization angle and polarization ratio information displayed over an image built using average light information. The PixelFormat is automatically changed in this mode as follows:

When PixelFormat is Mono8, the image is output as BayerRG8

When PixelFormat is Mono10, the image is output as BayerRG10

When PixelFormat is Mono10Packed, the image is output as BayerRG10Packed

5. ColorOnGray mode

This mode provides a pseudo-color overlay representing polarization angle and polarization ratio information displayed over a gray image. The PixelFormat is automatically changed in this mode as follows:

When PixelFormat is Mono8, the image is output as BayerRG8

When PixelFormat is Mono10, the image is output as BayerRG10

When PixelFormat is Mono10Packed, the image is output as BayerRG10Packed

Binning Function

The binning function allows you to combine the signal values of clusters of adjacent pixels to create improved virtual pixels. Using the function results in images with lower pixel resolution and higher sensitivity.

This camera performs both horizontal binning and vertical binning via digital addition or averaging processing.

The following four conditions must be met to use the binning function.

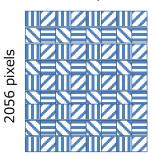
- 1. [PolarizeImageSelector] is [RawImage].
- 2. The ROI function, sequencer function, and binning function cannot be used at the same time.
- 3. PixelFormat is one of Mono8, Mono10, and Mono10p.
- 4. [VideoProcessBypassMode] is [Off].
- When horizontal binning only (2x1)

The signal values of the pixels having polarizers at the same angle are combined. The signal values of the two pixels indicated by the red frames in the following figure are combined.



The image data output from this camera becomes RawImage with 1232 pixels (horizontally) x 2056 pixels (vertically).



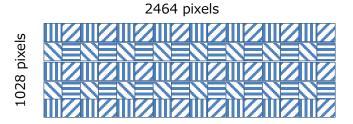


■ When vertical binning only (1x2)

The signal values of the pixels having polarizers at the same angle are combined. The signal values of the two pixels indicated by the red frames in the following figure are combined.

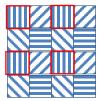


The image data output from this camera becomes RawImage with 2464 pixels (horizontally) \times 1028 pixels (vertically).

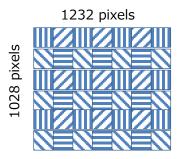


■ When horizontal and vertical binning (2x2)

The signal values of the pixels having polarizers at the same angle are combined. The signal values of the four pixels indicated by the red frames in the following figure are combined.



The image data output from this camera becomes RawImage with 1232 pixels (horizontally) \times 1028 pixels (vertically).



12-bit Output

With this camera, when VideoProcessBypassMode is enabled, output with PixelFormat as Mono12 or Mono12Packed is possible.

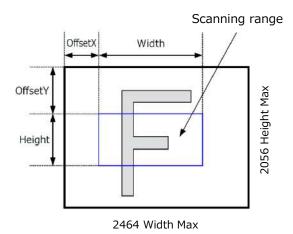
When VideoProcessBypassMode is enabled, video output is fixed to the RawImage mode and the binning function and ROI function cannot be used.

ROI (Regional Scanning Function)

The ROI (region of interest) function allows you to output images by specifying the areas to scan.

ROI Settings

Specify the area to scan by specifying width, height, and horizontal/vertical offset values under [ImageFormatControl].



You can increase the frame rate by specifying a lower height, as the number of lines scanned decreases. The setting ranges for the ROI function's readable area based on the Binning setting (Binning Horizontal, Binning Vertical) are as follows.

Width	Height
16 ~ 2464	2 ~ 2056
16 pixels / step	2 Lines / step
	100

Offset X	Offset Y		
0 ~ 2448	0 ~ 2054		
16 pixels / step	2 Lines / step		

Image Acquisition Controls

Perform operations and configure settings related to image acquisition in [AcquisitionControl].

The following acquisition modes are available on the camera.

AcquisitionMode	Description	
SingleFrame	Acquire a single frame when the [AcquisitionStart]	
	command is executed.	
MultiFrame	Acquire the number of frames specified in	
	[AcquisitionFrameCount] when the [AcquisitionStar	
	command is executed.	
Continuous	Acquire images continuously until the	
	[AcquisitionStop] command is executed.	

Changing the Frame Rate

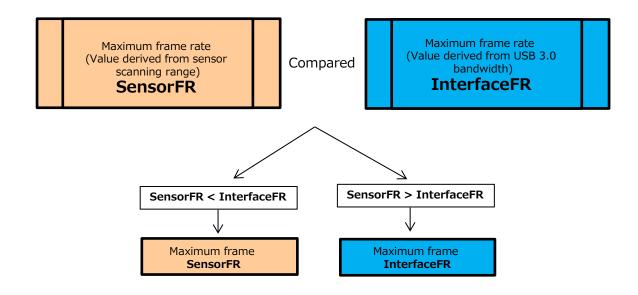
When [TriggerMode] is disabled, you can change the frame rate in [AcquisitionFrameRate].

Note

- The shortest frame period varies depending on the ROI, pixel format, and binning mode selected. The longest frame period is 0.125 Hz (8 sec.).
- When TriggerMode[FrameStart] is enabled, the [AcquisitionFrameRate] setting is disabled.

Maximum Frame Rate

The maximum frame rate is the smaller value between the SensorFR that is calculated from the readable range of the sensor and the InterfaceFR that is limited by the USB 3.0 bandwidth.



■ Maximum frame rate period formula

During continuous operation ([Frame Start] trigger is [Off] or [Exposure Mode] is [Off])

• Maximum frame rate of sensor output

SensorFR = $1 / \{ Hperiod \times (Height + 40) \}$

• Maximum frame rate by interface

InterfaceFR = 3000×1000000 / (Height × Width × Pack value)

• Maximum frame rate

FR_Cont = Min (Sensor FR, Interface FR)

When the exposure time is longer than the frame interval

• Maximum exposure time at maximum frame rate

MaxExposureTime TrOlrd = $(1 / FR Cont) - (14 \times H Period)$

Exposure time outside of frame interval

NonOverlapExposureTime = ExposureTime - MaxExposureTime_TrOlrd

However, NonOverlapExposureTime calculation results that are 0 or below will be considered as 0.

• Maximum frame rate

 $FR_ContLongExposure = 1/{(1/FR_Cont) + NonOverlapExposureTime}$

When [Frame Start] trigger is [On] and [Trigger OverLap] is [Off]

• Maximum frame rate of sensor output

Sensor $FR = 1 / \{H \text{ Period} \times (Height + 40)\}$

• Maximum frame rate by interface

Interface $FR = 3000 \times 1000000$ / (Height × Width × Pack value)

• Maximum frame rate

FR_Cont = Min (Sensor FR, Interface FR)

• Exposure time possible within frames

MaxOverlapTime_TrOloff = (1 / FR_Cont) - (1 / Sensor FR)

• Exposure time outside of frame interval

NonOverlapExposureTime_TrOloff = ExposureTime - MaxOverlapTime_TrOloff

However, NonOverlapExposureTime_TrOloff calculation results that are 0 or below will be considered as 0. For TriggerWidth, the trigger pulse is equivalent to ExposureTime.

• Maximum frame rate

FR_TrOloff = 1 / {(1 / FR_Cont) + NonOverlapExposureTime_TrOloff}

When [Frame Start] trigger is [On] and [Trigger OverLap] is [Readout]

• Maximum frame rate of sensor

Sensor $FR = 1 / \{H \text{ Period} \times (Height + 40)\}$

• Maximum frame rate by interface

Interface $FR = 3000 \times 1000000 / (Height \times Width \times Pack value)$

Maximum frame rate

FR Cont = Min (Sensor FR, Interface FR)

• Exposure time possible within frames

 $MaxOverlapTime_TrOlrd = (1 / FR_Cont) - (14 \times H Period)$

Exposure time outside of frame interval

NonOverlapExposureTime_TrOlrd = ExposureTime - MaxOverlapTime_TrOlrd However, NonOverlapExposureTime_TrOlrd calculation results that are 0 or below will be considered as 0. For TriggerWidth, the trigger pulse is equivalent to ExposureTime.

• Maximum frame rate

FR_TrOlrd = 1 / {(1 / FR_Cont) + NonOverlapExposureTime_TrOlrd}

Tap Geometry	H Period (μs)	Pack Value	
8 bit	5.93	8	
10 bit packed	6.99	10	
12 bit packed	6.99	12	
10 bit/12 bit	6.99	16	

ExposureMode

The following exposure modes are available on the camera.

ExposureMode	Description		
Off	Exposure control is not performed (free-running operation).		
	Mode in which control is performed using exposure time. Acquire		
	images using an exposure time configured beforehand on an external		
Timed	trigger.		
	Mode in which control of the exposure time is performed using the		
	pulse width of the trigger input signal. The exposure time will be the		
	same as the pulse width of the trigger input signal. This allows long		
TriggerWidth	exposure.		

[☼] The settings for exposure control and triggers are related to each other. Be sure to configure the settings described in "Trigger Control".

Actual Exposure Times

The shortest exposure times that can be configured are as follows.

Exposure Mode	Shortest exposure time	
Timed	14.7µs	
TriggerWidth	14.7µs	

- \cdot The actual exposure time will consist of the image sensor's offset duration (13.7 $\mu s)$ added to the setting configured on the camera.
- \cdot When [ExposureMode] is set to [Timed] and the exposure time is set to 1 $\mu s,$ the actual exposure time will be as follows.
- $1 \mu s + 13.7 \mu s$ (offset duration of image sensor) = 14.7 μs
- When [ExposureMode] is set to [TriggerWidth], the exposure is slightly longer than the width of the trigger signal. To achieve an exposure time of 14.7 μ s and the exposure time offset is 13.7 μ s, use 14.7 μ s 13.7 μ s = 1 μ s as the high or low time for the trigger signal.

Trigger Control

The camera allows the following controls to be performed via external trigger signals.

TriggerSelector	Description		
FrameStart	Start exposure in response to the external trigger signal input. Select		
	this to perform exposure control using external triggers.		
AcquisitionStart	Start image acquisition in response to the external trigger signal input.		
AcquisitionEnd	Stop image acquisition in response to the external trigger signal input.		
AcquisitionTransferStart	Output acquired images at a specified timing in response to an		
	external trigger signal input.		
	* There is a limit to the number of image frames that can be stored		
	internally. The limits for each image format are as follows. Acquired		
	images must be output to avoid exceeding these limits.		
	8 bit: Up to 8 frames		
	10 bit: Up to 4 frames		
	12 bit: Up to 4 frames		

• The settings for exposure control and triggers are related to each other. Be sure to configure the settings described in "ExposureMode".

Shortest Repetition Period for Triggers

The reciprocal of the maximum frame rate is the time required to output one frame. The shortest repetition periods for triggers cannot be lower than that value.

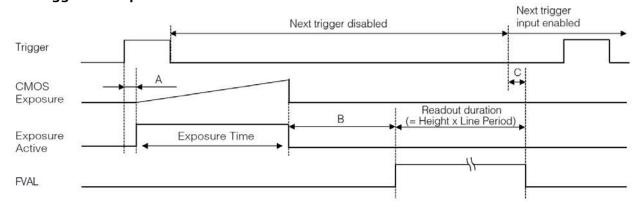
0	Shortest period of trigger			
Scanning range	8 bit	10 bit Packed	10 bit	
Full	13.426 ms	16.788 ms	26.920 ms	
ROI 2/3 (Height=1370)	8.918 ms	11.154 ms	17.905 ms	
ROI 1/2 (Height=1028)	6.671 ms	8.354 ms	13,411 ms	
ROI 1/4 (Height=514)	3.294 ms	4.123 ms	6.656 ms	
ROI 1/8 (Height=256)	1.671 ms	2.004 ms	3.266 ms	
Binning Vertical 2*	6.671 ms	8.345 ms	13.411 ms	

The above table indicates the shortest trigger periods for when [TriggerOverLap] is set to [Readout]. When [TriggerOverLap] is set to [Off], even when the exposure time is shorter than the frame period, the cycle may be extended.

■ When [ExposureMode] is [Timed]

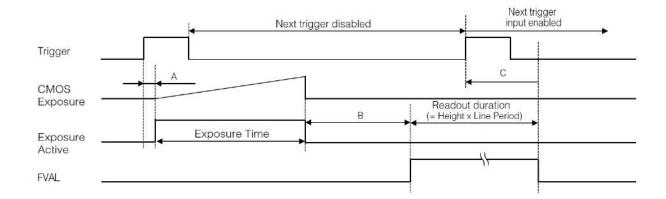
Example: When [TriggerSource] is set to [Line 5 - OptIn1] and [OptInFilterSelector] is set to [10 μs]

• TriggerOverlap : Off



PixelFormat	Sensor Dig Bit	Period from Trigger start edge to Exposure start [A] (usec)	Period from Exposure end to FVAL start [B] (usec)	Period FVAL end to next trigger start [C] (usec)
Mono8	12	25.1	201.8	1.9
Mono10Packed	12	28.3	238	6.7
Mono10	12	28.3	237	6.1

• TriggerOverlap : readout

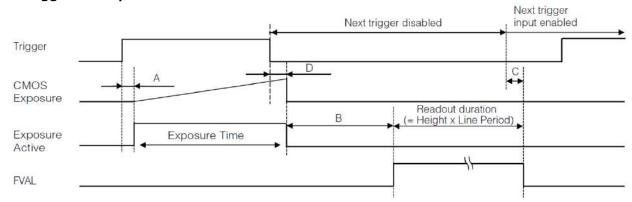


Pixel format	Sensor Dig Bit	Period from Trigger start edge to Exposure start[A](usec)	Period from Exposure end to FVAL start[B] (usec)	Period FVAL end to next trigger start[C](usec)
Mono8/BayRG8	12	25.1	201.8	13,500 – Exposure Time
Mono10 Packed/ BayRG10 Packed	12	28.3	238.0	16,900 – Exposure Time
Mono10/BayRG10	12	28.2	238.0	27,000 - Exposure Time

■ When [ExposureMode] is [TriggerWidth]

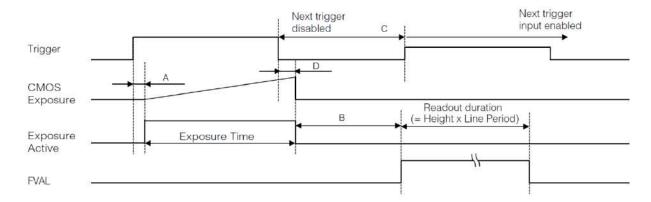
Example: When [TriggerSource] is set to [Line 5 - Optical In 1] and [OptInFilterSelector] is set to [10 μ s]

• TriggerOverlap : Off



Pixel format	Sensor Dig Bit	Period from Trigger start edge to Exposure start[A] (usec)	Period from Exposure end to FVAL start[B] (usec)	Period FVAL end to next trigger start[C](usec)	Period from Trigger end edge to Exposure end[D](usec)
Mono8/ BayRG8	12	25.1	201.8	2.2	25.1
Mono10 Packed/ BayRG10 Packed	12	28.3	238.0	6.9	28.3
Mono10/ BayRG10	12	28.3	238.0	6.5	28.3

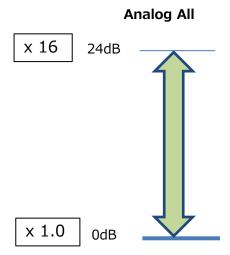
• TriggerOverlap : readout



Pixel format	Sensor Dig Bit	Period from Trigger start edge to Exposure start[A](usec)	Period from Exposure end to FVAL start[B] (usec)	Next trigger start prohibited period[C](usec)	Period from Trigger end edge to Exposure end[D](usec)
Mono8/ BayRG8	12	25.1	201.8	23.2	25.1
Mono10 Packed/ BayRG10 Packed	12	28.3	238.0	29.0	28.3
Mono10/ BayRG10	12	28.3	238.0	29.1	28.3

Gain Control

Adjust the [AnalogAll] (master gain) setting.



LineStatus

The line status function allows you to verify the status of external input/output signals. You can verify the status of the following signals.

- Line5-OptIn1, Line6-OptIn2
- NANDGate0In1, NANDGate0In2
- NANDGate1In1, NANDGate1In2
- Line1-TTLOut1, Line2-OptOut1
- TimestampReset

BlemishCompensation

Multiple defective pixels that are not adjacent to each other can occur on conventional CMOS sensor cameras.

This camera features a function that interpolates defective pixels using the surrounding pixels. Up to 256 pixels can be corrected for each of the three sensors. Pixel interpolation can be performed via automatic detection or point-by-point manual settings.

■ Automatic detection

Automatic detection can only detect lit defective pixels (i.e., white blemishes).

1 Shield the camera sensor.

If a lens is attached, use the lens cap as a shield, for example.

7 Configure the threshold level for defective pixel detection.

Up to 256 pixels can be corrected.

The threshold value is specified as a percentage.

The default setting is "10" with 10% of the full scale (100%) specified as the threshold value.

2 Execute [BlemishDetect] to start automatic detection.

After detection, the interpolation data is saved to the camera's internal memory.

To check the number of interpolated pixels after automatic detection

You can check the number of pixels interpolated via automatic detection by loading the BlemishNum data.

■ Manual configuration

1 Select the index in [BlemishCompensationIndex].

You can select from 0 to 255. However, configure the indexes in order starting with the smallest index. If you skip indexes while configuring settings, interpolation may not be performed.

2 Specify the pixel points for interpolation using the [BlemishCompensationPositionX] and [BlemishCompensationPositionY] settings.

You can configure values that are within the total effective pixel area. Specify pixels for which interpolation is not necessary as -1. If 0 is specified, the first line or first pixel will be interpolated.

Note

BlemishCompensationDataClear[BlemishCompensationIndex], you can return a specific pixel correction setting to the default value (storage not required).

3 Execute [BlemishStore].

Blemish compensation data will be stored.

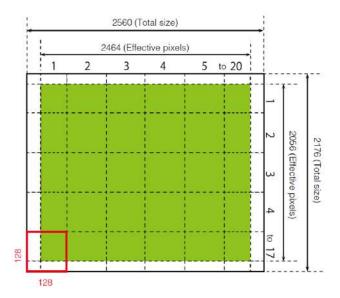
Set [BlemishEnable] to [True], and execute interpolation.

If it is set to [False], Blemish compensation is not effective.

ShadingCorrection

The shading correction is a function that corrects non-uniformity (i.e., shading) in the amount of light generated by the lens and lighting equipment. Using this function allows correction even if top, bottom, left, and right shading is not symmetrical in relation to the center of the screen (H, V).

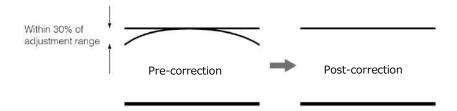
The size of the correction block is 20 (H) \times 17 (V) blocks and calculation errors in the correction data are minimized due to the small interpolation block. Each block is 128 \times 128 pixels. The total size of the blocks is 2560 (H) \times 2176 (V), but the actual number of effective pixels for the camera is 2464 (H) \times 2056 (V). The ineffective peripheral areas will be deleted internally on the camera automatically.



The following shading correction modes are available on the camera.

■ FlatShading

Correction is performed using the area of the screen with the highest brightness level as the reference, and adjusting the brightness levels of the other areas to match this level.



Caution

Proper correction is not possible under the following conditions.

- If an area with a brightness level that is more than 30% less than the reference level exists within the screen
- If the brightness level is saturated in parts or all of the screen
- If the area in the screen with the highest brightness level is 300 LSB or less (during 10-bit video output)

■ To use the shading correction function

Configure the settings as follows.

Item	Setting value	Description	
ShadingCorrectionMode	FlatShading	Select the shading correction mode.	
ShadingMode	User1, User2, User3, Off	Select the user area to which to save the	
		shading correction value.	

Display a white chart under a uniform light, and execute [PerformShadingCalibration].

Note

After shading correction is executed, the shading correction value is automatically saved to the user area selected in [ShadingMode].

Sequencer Function

The Sequencer function lets you define up to 128 index combinations of exposure time, gain, ROI, and other settings which can be stepped through each time a trigger is received. This is particularly useful for quickly capturing multiple exposures of objects under inspection to adjust for areas or components with significantly different levels of reflectance. You can specify the next index in the stepping sequence and the order in which indexes are executed. Multiple indexes can also be executed repeatedly.

Two operation modes (TriggerSequencer mode and CommandSequencer mode) are available for the Sequencer function.

Note

The following four conditions must be met to use the Sequencer function.

- 1. [PolarizeImageSelector] is [RawImage].
- 2. Sequencer Width, Sequencer Offset X function, and Sequencer H Binning function cannot be used at the same time.
- 3. Sequencer Height, Sequencer Offset Y function, and Sequencer V Binning function cannot be used at the same time.

About indexes (imaging conditions)

Up to 128 indexes can be configured. The following settings can be configured for each index. However, SequencerFrameNumber and SequencerSetNext can only be configured in TriggerSequencer mode.

Trigger Sequencer mode

With this mode, the Sequencer Trigger "pattern" is predetermined by the user. The user defines up to 128 different "indexes." The items indicated in the above index can be configured for each index. The operation of this mode is controlled using the following five commands.

[SequencerSetActive]

This allows you to confirm the currently configured index number.

[SequencerSetStart]

This configures the index number to execute at the start of TriggerSequencer mode.

[SequencerReset]

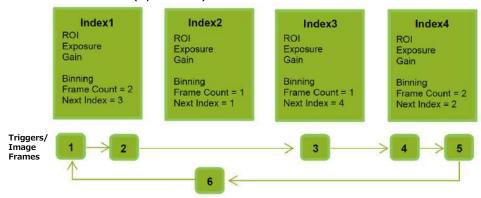
During TriggerSequencer mode operation, this switches the index number to be executed to that specified in [SequencerSetStart].

[SequencerRepetition]

This parameter applies to TriggerSequencer patterns which include an index whose [SequencerROINextIndex] is set to 0 (OFF). When the index whose [SequencerROINextIndex] is set to 0 (OFF) is finished executing, the value of Sequencer Repetition (range = 1-255) is decremented internally. If the result of the decrement is not zero, the TriggerSequencer pattern starts over from the index specified in SequencerSetStart. If the result of the decrement is zero, the status changes to Acquisition Stop and external triggers are not accepted.

Sample TriggerSequencer mode operation

User-defined Indexes (up to 128)



- Specify "1" in [SequencerSetStart], and start TriggerSequencer mode with index 1.
- **7** Capture a 2-frame image with the first and second triggers.
- For the next index, configure index 3 specified in [SequencerSetNext], and capture an image with the number of frames (number of triggers) specified in [SequencerFrameNumber].

Proceed to sequence from index 4 to index 2 to index 1.

Note

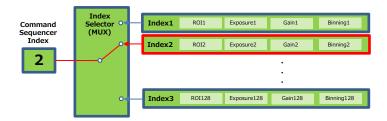
In addition to repeating multiple conditions as in the above example, you can specify "0" (which indicates the end of TriggerSequencer mode) in [SequencerSetNext] of index 2, and specify the number of repetitions in [SequencerRepetition].

Command Sequencer mode

As with TriggerSequencer mode, you can define up to 128 indexes beforehand in this mode. Set [SequencerCommandIndex] to point to one of your pre-configured indexes. This index will be executed on each trigger, until it is changed to point to a different index, typically by your vision application. In this way, Command Sequencer mode allows you to programmatically adjust your sequence in response to image analysis or input from other sensors.

Note

- The same index table will be executed for subsequent triggers unless the [CommandSequencerIndex] value is changed.
- [SequencerFrameNumber] and [SequencerSetNext] cannot be used in CommandSequencer mode.



Delayed Readout

Delayed readout allows images captured by a [FrameStart] trigger command to be stored temporarily inside the camera (delayed readout buffer) and read out using a [AcquisitionTransferStart] trigger after capture. This function is useful when executing triggers simultaneously on multiple cameras.

Note

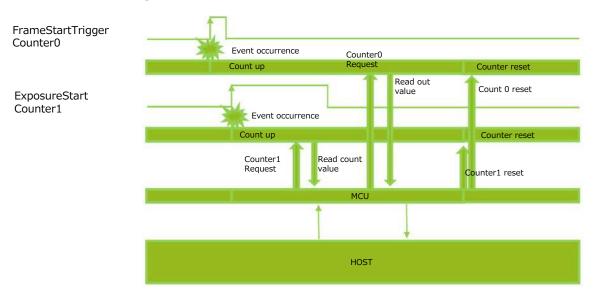
This function imposes a heavy processing load on the network bandwidth, as images from multiple cameras are read out simultaneously. The number of frames that can be stored for delayed readout depends on PixelFormat.

For details, see "Trigger Control".

CounterAndTimerControl Function

The counter function counts up change points in the camera's internal signals using the camera's internal counter, and reads that information from the host side. This function is useful for verifying error conditions via the count value using internal camera operations. Counting is performed at frame trigger, frame start, exposure start, and exposure transfer end, and by comparing these values, you can determine the internal camera state at which missed triggers will occur.

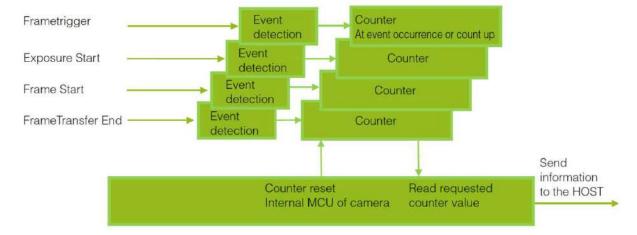
■ Counter occurrence diagram



Note

You can reset a specific counter's count value by executing CounterReset[Counter0, Counter1, Counter2, Counter3].

■ Internal camera blocks



■ To use the counter function

Configure the settings as follows. Three counters can be configured (Counter 0 to 2).

		Setting value /	
Item		selectable range	Description
Counter 0 to 2		Counter 0 to 2	Select the counter.
Counter 0 to 2 Event Source		Off,	Select the counter event signal
		Frame Trigger, Frame Start,	for which to read the count
		Exposure Start, Exposure	value.
		Transfer End	
	Counter 0 to 2 Event Activation	Rising Edge or Falling Edge	Specify the timing at which to
			count.

^{*} The three counter event signals are always counted up internally on the camera.

Chunk Data Function

The Chunk Data function adds camera configuration information to the image data that is output from the camera. Embedding camera configuration information in the image data allows you to use the serial number of the camera as a search key and find specific image data from among large volumes of image data. In addition, when images are shot with a single camera in sequence under multiple setting conditions, you can search for images by their setting conditions.

The following information can be added to image data as chunk data.

■ Configuring Chunk Data

1 Set [ChunkModeActive] to [True].

2 Select the items of information you want added to image data with [ChunkSelector], and set [ChunkEnable] from [False] to [True].

Note

When [ChunkModeActive] is set to [True], [ChunkImage] is automatically set to [True].

Caution =

The Chunk Data function settings cannot be changed during image output. To change the settings, stop Acquisition.

*) For items that can be added to image data as Chunk Data, refer to [m) ChunkDataControl] in the setting item list.

Video Process Bypass Mode

The video process bypass mode is a function that bypasses internal video processing on the camera. When bypass is enabled, the sensor output and camera output data can be set to the same bit width. Operation using 12-bit outputs must be performed in bypass mode.

Functions disabled in Video Process Bypass mode BlackLevel, Shading, Binning(H, V) Polarize Image Selector (Fixed to Raw Image)

PixelFormat available only in Video Process Bypass mode Mono12, Mono12Packed

Setting List

Feature Properties

Item	Setting range	Default value	Description
a) Device Control			Display/configure information related to
			the device.
Device Vendor Name	_	"JAI Corporation"	Display the manufacturer name.
Device Model Name	_	GO-5100MP-USB	Display the model name.
Device Manufacturer Info	_	See the possibilities	Display the manufacturer information.
Device Version	_	_	Display the hardware version.
Device Firmware Version	_	_	Display the firmware version.
Device Serial Number	_	_	Display the device ID.
Device User ID	Any	_	Set the user ID (64bytes) for the camera.
Device Temperature Selector	Mainboard	Mainboard	Select the area of the camera's interior for
			which to display the temperature sensor's
			reading. (fixed Mainboard)
Device Temperature(C)	_	_	Display the internal temperature (°C) of
			the camera.
Device Reset	_	_	Reset the device.
			(After the camera receives this command, it returns
			an ACK response. Then, execute reset.)

Item	Setting range	Default value	Description
b) mage Format Control		•	Configure image format settings.
Sensor Width	2464	2464	Display the maximum image width.
Sensor Height	2056	2056	Display the maximum image height.
Width Max	2464	2464	Display the maximum image width.
Height Max	2056	2056	Display the maximum image height.
Width	BinningHorizontal 1: 16~2464 BinningHorizontal 2: 16~1232	2464	Set the image width.
Height	BinningVertical 1: $1 \sim 2056$ step 2 BinningVertical 1: $1 \sim 1028$ step 2	2056	Set the image height.
Offset X	BinningHorizontal 1: $0\sim$ 2448 BinningHorizontal 2: $1\sim$ 1216	0	Set the horizontal offset.
Offset Y	BinningVertical 1: $0 \sim 2055$ BinningVertical 1: $0 \sim 1027$	0	Set the vertical offset.
Binning Horizontal Mode	Average, Sum	Sum	Set the addition process to be used during horizontal binning.
Binning Horizontal	1,2	1	Set the number of pixels in the horizontal direction for which to perform binning.
Binning Vertical Mode	Average, Sum	Sum	Display the addition process to be used during vertical binning.
Binning Vertical	1,2	1	Set the number of pixels in the vertical direction for which to perform binning.
Pixel Format Test Pattern	8 Bit Monochrome 10 Bit Monochrome 10 Bit Monochrome Packed 12 Bit Monochrome 12 Bit Monochrome Packed Off,	Mono8	Set the pixel format. The following mode are enabled when [VideoProcessBypassMode] is set to [On]. 12 Bit Monochrome 12 Bit Monochrome Packed Select the test image.
	GreyHorizontalRamp, GreyVerticalRamp, GreyHorizontalRampMoving		

Item	Setting range	Default value	Description
c) cquisition Control	Setting runge	Delaute value	Configure image capture settings.
Acquisition Mode	Single Frame,	Countinuous	Select the image capture mode.
Troquisius: Trous	Multi Frame,		coloct the image captairs mode.
	Continuous		
	Continuous		
Acquisition Start	_	_	Start image capture.
Acquisition Stop	_	_	Stop image capture.
AcquisitionFrameCount	1~255	1	In [MultiFrame] mode, set the number of
			frames to capture.
AcquisitionFrameRate(Hz)	0.125~74.0192	74.0192	Set the frame rate as a frequency. (unit:
			Hz)
			The maximum value varies depending on
			the PixelFormat and ROI settings.
			the Fixen office and Not settings.
Trigger Selector	Acquisition Start,	Frame Start	Select the trigger operation.
	Acquisition End,		
	Frame Start, Acquisition Transfer Start		
Tuin non Mode	·	044	Colort the trice and a
Trigger Mode Trigger Software	Off, On	Off	Select the trigger mode. Execute a software trigger.
Trigger Source	Low	Line 5 - Optical In 1	Select the trigger signal source.
I Ingger Source	High	Ente 5 Optical III I	Select the trigger signal source.
	Software		
	Pulse Generator0		
	User Output 0		
	User Output 1		
	Line5 - Optical In 1 NAND0Out		
	NAND1Out		
Trigger Activation	Rising Edge	Rising Edge	Select the polarity of the trigger signal
	Falling Edge		(i.e., location of signal at which trigger is applied).
Trigger Overlap	Off, ReadOut	Off	Select the trigger overlap operation.
ExposureMode	Off, Timed,	Timed	Select the exposure mode.
	Trigger Width		
ExposureTime	1 ~	_	Set the exposure time. The specifiable
			range varies depending on the
			[StartTriggerMode] and
			[PixelFormat] setting.
			[. men erman] estaing.
ExposureAuto	Off, Continuous	Off	Set whether to enable auto exposure.
Item	Setting range	Default value	Description
d) nalog Control			Configure analog control settings.
Gain Selector	Analog All	Analog All	Select the gain to configure.
Gain	x1.0 ~ x16.0	x1.0	Set the gain value for the gain setting
			selected in [GainSelector].
Black Level Selector	Digital All	Digital All	Select the black level to configure.
Black Level	-133~255	0	Set the black level value.
GainAuto	Off,	Off	Enable/disable gain auto adjustment.
	Continuous		[Once] automatically changes to [Off]
			when the signal level converges once.

Item	Setting range	Default value	Description
e) Digital I/O contr		•	Configure settings for digital input/output.
Line Selector	Line2-Opt Out 1, Line3-Opt Out 2, Line5-Opt In 1, Time Stamp Reset, NAND Gate 0 In 1, NAND Gate 0 In 2, NAND Gate 1 In 1, NAND Gate 1 In 1,	Line2-Opt Out 1	Select the input/output to configure.
Line Mode	Input, Output	_	Display the input/output status (whether it
Line Inverter	True, False	False	is input or output). Enable/disable polarity inversion for the selected input signal or output signal.
Line Status	True, False	-	Display the status of the input signal or output signal (True: High, False: Low).
Line Source	Low, High, Acquisitiion Trigger Wait, Acquisition Active, Frame Trigger Wait, Frame Active, Exposure Active, FVAL, LVAL, PulseGenerator0, User Output 0, User Output 1, Line5 - Opt In 1, NANDOOut, NAND1Out,	Low	Select the line source signal for the item selected in [LineSelector].
Line Format	_	Opto Coupled	Display the signal format.
Line Status All		0×00	Display the input/output signal status. The state is shown with 16 bits. Bit assignments are as follows. [0] (unus [1] Line2 - OptO [2] Line3 - OptO [3] (unus [4] Line5 - Opt I [5], [6], [7], [8], [9], [10] (unused) [11] Time Stamp R [12] NAND Gate 0 [13] NAND Gate 0 [14] NAND Gate 1
User Output Selector	User Output 0 User Output 1	User Output 0	Set the UserOutput signal.
User Output Value	True, False	False	Set the value for the UserOutput selected in [UserOutputSelector].

項目	設定範囲	初期値	説明
f) ounter And Timer Control	政定型四	初知但	Configure counter settings.
ouncer And Timer Control			(This camera only supports counter functions.)
Counter0 Event Source	Off,	Off	Assign the counter event signal for which
Countero Event Source	Frame Trigger,		you want to read the count value to a
	Frame Start,		'
	Exposure Start,		dedicated counter, and read the value.
	Frame Transfer End		
Counter0 Event Activation	Rising Edge	_	Set the count timing.
	Falling Edge		
Counter0 Reset	_	_	Reset the counter.
Counter0 Refresh	_	_	Update the count value.
Counter0 Value	_	0	Display the count value.
Counter0 Status	Counter Active	Counter Active	Display the counter status.
			CounterIdle: Idle
			CounterActive: Counting
			CounterOverflow: Count value exceeded the
			mazimum value
Counter1 Event Source	Off,	Off	Assign the counter event signal for which
	Frame Trigger,		you want to read the count value to a
	Frame Start, Exposure Start,		dedicated counter, and read the value.
	Frame Transfer End		
Counter1 Event Activation	Rising Edge Falling Edge	_	Set the count timing.
	I allilig Luge		
Counter1 Reset	_	_	Reset the counter.
Counter1 Refresh	_	_	Update the count value.
Counter1 Value		0	Display the count value.
Counter1 Status	Counter Active	Counter Active	Display the counter status.
			CounterIdle: Idle CounterActive: Counting
			CounterOverflow: Count value exceeded the
			mazimum value
Counter2 Event Source	Off,	Off	Assign the counter event signal for which
	Frame Trigger,		you want to read the count value to a
	Frame Start,		dedicated counter, and read the value.
	Exposure Start,		dedicated counter, and redu the value.
	Frame Transfer End		
Counter2 Event Activation	Rising Edge	_	Set the count timing.
	Falling Edge		
Counter2 Reset	_	_	Reset the counter.
Counter2 Refresh	_	_	Update the count value.
Counter2 Value	_	0	Display the count value.
Counter2 Status	Counter Active	Counter Active	Display the counter status.
			CounterIdle: Idle
			CounterActive: Counting CounterOverflow: Count value exceeded the
			mazimum value
Item	Setting range	Default value	Description
g) User Set Control	Setting range	Delault value	Configure user settings.
g/ Oser Set control			Comigure user settings.
	D-flb	D - 6 It	
User Set Selector	Default, UserSet1,	Default	Select the user settings.
	UserSet2,		
	UserSet3		
L			
User Set Load	0(default), 1, 2, 3	-	Load user settings.
			(If 0 is specified, the factory default setting is read.)
User Set Save	1 2 2		Save the current esting values as use:
User Set Save	1,2,3	_	Save the current setting values as user
			settings.

Item	Setting range	Default value	Description
h) equencer Control	Setting range	Delault value	Configure sequencer settings.
Sequencer Mode	Off, On	Off	Enable(On)/disable(Off) [SequencerMode].
Sequencer Mode	OII, OII	Oil	[SequencerMode].
Sequencer Mode Select	Trigger Sequencer Mode,	Trigger Sequencer Mode	Select the sequencer mode.
	Command Sequencer Mode		
Sequencer Configuration Mode	Off, On	On	Select [On] to change the settings within
			the index.
Sequencer Set Selector	1~128	1	Select the index number to configure.
'			
Sequencer Frame Number	1~255	1	Set the number of frames to display for the
Sequencer Frame Number	233		selected SequencerIndex.
			(Enabled only for TriggerSequencer.)
Sequencer Set Next	0~128	_	Set the next index to be displayed for the
Sequencer Set Next	0,0120	_	
			selected SequencerIndex.
			(Enabled only for TriggerSequencer.) If 0 is specified, the operation of Sequencer is
			stopped.
Coguangar Width	16~2464	2464	Set the width of the selected
Sequencer Width	10~2404	2404	
			SequencerIndex.
Sequencer Height	1~2056	2056	Set the height of the selected
			SequencerIndex.
			Sequencer mack.
Sequencer OffsetX	$0 \sim 2448$	0	Set the horizontal offset value for the
			selected SequencerIndex.
Sequencer OffsetY	0 ~ 2055	0	Set the vertical offset value for the selected
			SequencerIndex.
Sequencer Gain	100~1600	100	Set the GainAnalogAll value.
Sequencer Gain	100/~1600	100	Set the Gamanalogan value.
Sequencer Exposure Time	1 ~ 8000000	_	Set the exposure time for the selected
Sequencer Exposure Time			SequencerIndex.
			Sequencerindex.
Sequencer Black Level	-133~255	0	Set the BlackLevelDigitalAll for the selected
	100 100		SequencerIndex.
			Sequencer muex.
Sequencer H Binning	1,2	1	Set the H Binning for the selected
	1-7-	<u> </u>	SequencerIndex.
			Binning Horizontal Mode setting is applied in binning
			mode.
	4.3	_	
Sequencer V Binning	1,2	1	Set the V Binning for the selected
			SequencerIndex.
			Binning Vertical Mode setting is applied in binning
			mode.
Sequencer Repetition	1~255	1	Set the repeat count for the sequencer.
	4 400	-	5. 1
Sequencer Set Active	1~128	1	Displays the sequencer set number.
Sequencer Command Index	1~128	1	Set this to change the SequencerIndex.
			(Enabled only for CommandSequencer.)
Sequencer Set Start	1~128	1	Specify the first index number to switch to when
			starting [TriggerSequencerMode].
Sequencer Reset	 	 	In [TriggerSequencerMode], reset the current index
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			number to the number configured in
			[SequencerSetStart].
	1	1	

Item	Setting range	Default value	Description
i) ChunkDataControl			Configure chunk control settings.
Chunk Mode Active	True, False	False	Set whether to enable ChunkData.
Chunk Selector	Image Offset X, Offset Y, Width, Height, Pixel Format, TimeStamp, Line Status All, ExposureTime, Gain All, Black Level All, Sequencer Set Active, Frame Trigger Counter, Exposure Start Counter, Frame Start Counter, Frame Transfer End Counter, Line Status All On FVAL Start, Device Temperature, Device Serial Number, Device User ID	OffsetX	Select the ChunkData to be added.
ChunkEnable	True, False	False	Select whether to output ChunkData. Default: Only [ChunkImage] is [True].
Item	Setting range	Default value	Description
j) Test Control			·
Test Pending Ack (ms)	_	_	PendingAck function test command. The camera waits for TestPendingAck (ms) time and returns an Ack response.
Item	Setting range	Default value	Description
k) ransportLayerControl			Display information on transport layer control.
PlayloadSize (B)			Display the payload size.
DeviceTapGeometry	_	Geometry_1X_1Y	Set the transfer method (tap configuration) of images transferred from the camera at one time.

	Item	Setting range	Default value	Description
17	PulseGenerator	Setting range	Delault value	·
-	ock Pre Scaler	1~4096	165	Configure pulse generator settings.
Cit	ock Pre Scalei	1,~4090	105	Set the division value for the prescaler (12
				bit) using PixelClock as the base clock.
Ļ		0.010107 74.05	0.45	
Pu	lse Generator Clock (MHz)	0.018127~74.25	0.45	Set the clock used for the pulse generator.
				This value is calculated using the
				[ClockPreScaler] value as a base.
Du	lse Generator Selector	Pulse Generator 0	Pulse Generator 0	Select the pulse generator.
Fu	ise deficiator selector	ruise deficiator o	ruise Generator o	Select the pulse generator.
-	Dulas Caramatan Lanath	1 1040575	20000	Cat the manifestory and the cat of the cat o
	Pulse Generator Length	1~1048575	30000	Set the maximum count-up value as a
				clock count.
	Pulse Generator Length (ms)	0.00222222~2330.17	66.6667	Set the maximum count-up value in
				milliseconds.
				This value is calculated using the
				[PulseGeneratorLength] value as a base.
				The setting range varies depending on the
				[ClockPreScaler] value.
	Pulse GeneratorFrequency (Hz)	0.429154~450000	15	Set the maximum count-up value as a
	also serierater requerie, (riz)	0.12920. 100000		· ·
				frequency.
				This value is calculated using the [PulseGeneratorLength] value as a base.
				[FulseGenerator Length] value as a base.
	Pulse Generator Start Point	0 ~ 1048575	0	Set the start point of the High interval as a
				clock count. When the counter reaches this
				value, the output will be 1.
				value, the output will be 1.
	Pulse Generator Start Point	0.002222~2330.166666	0	Set the start point of the High interval in
	(ms)			milliseconds.
	(113)			When the counter reaches this value, the output will
				be 1.
				The setting range varies depending on the
				[ClockPreScaler] value.
	Pulse Generator End Point	1 ~ 1048575	15000	Set the start point of the Low interval as a
		1 10.0070	15555	clock count.
				When the counter reaches this value, the output will
				be 0.
	Pulse Generator End Point (ms)	0.002222~2330.166666	33.3333	Set the start point of the Low interval in
	r disc deficiator End rount (ms)		33.3333	,
				milliseconds.
				When the counter reaches this value, the output will
				be 0. The setting range varies depending on the
				[ClockPreScaler] value.
	Pulse Generator Pulse Width	0.002222~2330.166666	33.3333	Display the High interval width of the pulse
1			55.555	
	(ms)			in milliseconds.
				The duration between the Start Point and End Point is
				calculated. The setting range varies depending on the [ClockPreScaler] value.
				Clock rescaler j value.
	Pulse Generator Repeat Count	0 ~ 255	0	Set the repeat count for the counter.
				When this is set to [0], a free counter is enabled with
				no repeat limit.
1				

Pulse Generator Clear Activation	Off, LevelHigh, LevelLow, RisingEdge, FallingEdge	Off	Set the clear signal condition for the count clear input of the pulse generator.
Pulse Generator Clear Source	Low, High, Acquisitiion Trigger Wait, Frame Trigger Wait, Frame Active, Exposure Active, FVAL, LVAL, User Output 0 User Output 1 Line5 - Opt In 1 NANDO Out	Low	Select the count clear input signal source.
Pulse Generator Clear Inverter	True, False	False	Select whether to invert the polarity of the count clear input signal.
Pulse Generator Clear Sync Mode	Async Mode, Sync Mode	Async Mode	Select the sync mode for the count clear input signal.

Item	Setting range	Default value	Description
m) AI Custom Contro	I ALC		Configure JAI ALC settings. These settings
			are also used for AGC (auto gain control).
ALC Reference	10 ~ 95	50	Set the target level for ALC. (unit: %)
			(, ,
ALC Aven Colomban	Low Right,	Law Dialet	Colort the area for which to configure
ALC Area Selector	Low Mid-Right,	Low Right	Select the area for which to configure
	Low Mid-Left,		[ALCAreaEnable].
	Low Left,		
	Mid-Low Right,		
	Mid-Low Mid-Right,		
	Mid-Low Mid-Left,		
	Mid-Low Left,		
	Mid-High Right,		
	Mid-High Mid-Right, Mid-High Mid-Left,		
	Mid-High Left,		
	High Right,		
	High Mid-Right,		
	High Mid-Left,		
	High Left		
ALC Area Enable	True, False	True	Enable/disable the photometry area
			selected in [ALCAreaSelector].
ALC Area Enable All	True, False	True	True: Operate ALC with all areas
			designated as photometry areas,
			regardless of the individual
			enabled/disabled photometry area
			states configured in
			[ALCAreaSelector].
			False: Operate ALC according to the
			individual enabled/disabled
			photometry area states configured
			in [ALCAreaSelector].
ASC Min.	$100 \sim 13426$	100	Set the minimum value for the
			ExposureAuto(ASC) control range.
ASC Max.	$101 \sim 13427$	13427	Set the maximum value for the
			ExposureAuto(ASC) control range.
AGC Min.	$100 \sim 1599$	100	Set the minimum value for the
		1,555	GainAuto(ASC) control range.
AGC Max.	$101\sim1600$	1600	Set the maximum value for the
100/100 0 : 10 :	1 0	1	GainAuto(ASC) control range.
AGC/ASC Control Speed	1 ~ 8	4	Set the response speed for AGC/ASC.
			(8 is the fastest.)
ALC Status	Off, ASC, AGC	_	Allows confirmation of the current
			operation area during ALC operation.
L			operation area during ALC operation.

Item	Setting range	Default value	Description
n) AI Custom Control Blen			Configure settings for JAI white blemish
			correction.
Blemish Enable	True, False	True	Enable/disable blemish correction.
Blemish Detect	_	_	Execute blemish detection.
Blemish Detect Threshold	$1 \sim 100$	10	Set the blemish detection threshold.
Blemish Compensation Index	0 ~ 255	0	Select the index for the target blemish
			coordinates
			(BlemishDataPosition X/Y).
Blemish Compensation Positio	nX -1 ~ 2463	-1	Display the X coordinate (horizontal pixel
			position) of the target blemish selected in
			[BlemishCompensationIndex].
			You can also manually enter the X coordinate of the
			blemish you want to correct.
Blemish Compensation Positio	nY -1 ~ 2055	-1	Display the Y coordinate (vertical pixel
			position) of the target blemish selected in
			[BlemishCompensationIndex].
			You can also manually enter the Y coordinate of the
			blemish you want to correct.
Blemish Compensation Number	er 0 ~	_	Display the number of target blemishes.
Item	Setting range	Default value	Description
o) AI Custom Control Sha		T	Configure shading correction settings.
Shading Correction Mode	Flat Shading	Flat Shading	Select the shading correction method.
Shading Mode	Off,	Off	Cat the area to which to any on bading
Shading Mode	•	OII	Set the area to which to save shading
	User1,		correction data.
	User2,		When this is set to [Off], shading
	User3		correction data is not saved.
Perform Shading Calibration			Execute shading correction.
			_
Shading Detect Result	_	-	Display the shading correction results.

Item	Setting range	Default value	Description
p) AICustomControlPolarized	Detting range	Delaute value	Configure controling polarization settings.
Polarize Image Selector	Raw Image,	Raw Image	Set the video output mode.
	Four Polarize Element,		·
	Four Functions,		
	Color on Picture,		
	Color on Gray		
Panel1 Selector	Polarize Angle,	_	This mode allows you to set the image to
	Polarize Ratio, Diffused Light,		output by assigning any of the following
	Polarized Light,		five information items to each area of the
	Average Light		screen divided into four.
Panel2 Selector	Polarize Angle,	_	The five information items are as follows.
. a.i.e. z delegge	Polarize Ratio,		PolarizeAngle,
	Diffused Light,		PolarizeRatio,
	Polarized Light,		DiffusedLight,
	Average Light		
			PolarizedLight,
Panel3 Selector	Polarize Angle,	-	AverageLight
	Polarize Ratio,		
	Diffused Light,		Panel 1 to 4 show the 4 division positions
	Polarized Light, Average Light		as shown below.
	Treating Light		
			Panel1 Selector : top left
Panel4 Selector	Polarize Angle,	_	Panel2 Selector: top right
	Polarize Ratio,		Panel3 Selector : bottom left
	Diffused Light, Polarized Light,		Panel4 Selector: bottom right
	Average Light		Pariety Selector : Bottom right
	/ Wordge Light		
Reflection Adjust [%]	50 ∼ 200 % step 10	100	The ratio for removing the polarized light
			component can be changed by adjusting
			Reflection Adjust.
			If ReflectionAdjust is set higher, DiffusedLight with
			more of the polarized light component removed can
			be obtained.
Item	Setting range	Default value	Description
q) AICustomControlMisc			Configure settings for other JAI functions.
VideoProcessBypassMode	Off, On	Off	Enable/disable VideoProcessBypass mode.
VideoriocessBypassinode	OII, OII		Litable/disable videorrocessbypass mode.
Trigger Option	Off	Off	
OptIn Filter Selector	10μs,		Select the surge protection filter
Spear Fines Sciences	100μs,		Scient the surge protection inter
	500μs,		
	1ms,		
	5ms,		
	10ms		
Video Send Mode	Normal Mode,	Normal Mode	Display the [VideoSendMode].
	Trigger Sequencer Mode, Command Sequencer Mode		
	Sommand Sequencer Mode		
Sensor LVDS Ch Num	8	8	Display the number of sensor output LVDS
<u> </u>	100" 100"	100:	channels.
Sensor Digitization Bits	10Bits, 12Bits	10Bits	Display the resolution per pixel of sensor
	1	<u> </u>	output.

Miscellaneous

Troubleshooting

Check the following before requesting help. If the problem persists, contact your local JAI distributor.

■ Power supply and connections

Problem	Cause and solution
The POWER/TRIG LED remains lit amber and	Camera initialization may not be complete
does not turn green, even after power is	due to lack of a network connection. Check
supplied to the camera.	the 12-pin power cable connection.

■ Image display

Problem	Cause and solution
Gradation in dark areas is not noticeable.	Use the gamma function to correct the
	display.
	As the light-emitting properties of the
	monitor are not linear, the entire image may
	be darker or the gradation in the dark areas
	may be less noticeable when camera outputs
	are displayed without processing. Using the
	gamma function performs correction to
	produce a display that is close to linear.
	For details, see "Gamma Function".

■ Settings and operations

Problem	Cause and solution
Settings cannot be saved to user memory.	You cannot save to user memory while
	images are being acquired by the camera.
	Stop image acquisition before performing the
	save operation.
I want to restore the factory default settings.	Load [Default] under [User Set Selector] in
	the [Feature Properties] tab to restore the
	factory default settings.

Specifications

	1	Item	GO-5100MP-USB		
Scanning system			Progressive scan, 1 tap		
Synchronization			internal		
Interface			USB 3 Vision compatible		
Image sensor			monochrome CMOS image sensor with a four-directional polarization grid		
Image size (effective image)			2/3-inch 8.5mm(H) x 7.09mm(V) : 11.1mm(diagonal)		
Pixel size			3.45 μm (H) x 3.45μm(V)		
Effective ima	ige pixel (Image sei	nsor)	2464(H) x 2056(V)		
Acquisition	8bit	Mono8	74.0 fps		
Frame Rate	10 Packed	Mono10Packed	59.2 fps		
	12bit Packed	Mono12Packed	49.0 fps		
(max)	10/12bit UnPacked	d Mono10, Mono12	37.0 fps		
MVA1288 p	arameters	•			
Absolute sen	sitivitv		T.B.D.		
Maximum SN	•				
i idxiii i di	1	Full	2464(H) x 2056(V)		
		Width	()		
			16 ~2464 pixels, 16 pixels/step		
Digital	ROI	Offset X	0 ~2448 pixels, 16 pixels/step		
Digital		Height	1 ∼2056 lines, 2 lines/step		
image		Offset Y	0 ∼2054 lines, 2 lines/step		
output			Mono8, Mono10, Mono10Packed,		
format			Mono12, Mono12Packed		
	Pixel Format		*When the video output mode is ColorOnPicture mode or ColorOnGray mode.		
			BayerRG8, BayerRG10, BayerRG10Packed		
			Enjament Superior Superior descu		
Acquisition M	1ode		Continuous / Single Frame / Multi Frame (1 \sim 255)		
	Acquisition		Acquisition Start / Acquisition Stop		
rigger	Exposure		Frame Start		
Selector	Transfer		AcquisitionTransfer Start (delayed readout)		
S			,		
	for trigger noise)		5 steps (10 μs(Typ), 100 μs, 500 μs, 1ms, 5ms, 10ms)		
rigger over			Off / Read out		
rigger input	t signals		Line 5 (Opt In)、Software、PG0、NAND Out 0/1、Action 1/2		
	Timed		14.7 μ s (min) \sim 8 s (max) variable unit : 1 μ s		
xposure	Timed		❖ Performance verified for up to 1 second.		
4ode					
Touc	Trigger Witdh		14.7 μs (min) \sim ∞ s (max) variable unit : 1 μs		
			❖ Performance verified for up to 1 second.		
			Normal Mode, Trigger Sequencer Mode,		
/ideo send n	node				
			Command Sequencer Mode, Multi Mode		
Digital I/O			Line Selector(6P): GPIO IN / GPIO OUT		
	Default level		33LSB@10bit		
Black Level			0 ∼ 100 @10bit		
	Video level adjustr	ment range	1 1 2 111		
adjustment			-33 LSB \sim +64LSB against reference level (during 10bit output)		
	Adjustment range		1 STEP = 0.25LSB		
	1		10121 0120205		
Gain			$0 ext{dB} \sim 24 ext{dB}$		
adjustment	Manual adjustmen	it range	1 step = \times 0.01 (0.005dB \sim 0.08dB:varies by setting value)		
			(
			Dotoet white blomishes using the selection		
	Detection		Detect white blemishes using threshold values		
Blemish			(black blemish correction performed only at factory)		
orrection			Interpolation using nearby pixels		
	Correction		, , , , , , , , , , , , , , , , , , , ,		
	Compostable		(continuous blemishes not corrected)		
(il)	Correctable pixels		256 pixels		
ibration res			10G (20 Hz ~ 200 Hz X-Y-Z direction)		
mpact resist	tance		80G		
		Input range	DC + 12 V \sim + 24 V \pm 10% (Via input terminal)		
	6-pin connector	Dawor canguration	4.2 M (han) (-1.12 M in-rat fall -in-l)		
Power		Power consumption	4.2 W (typ.) (at 12 V input, full pixel)		
supply		Input range	DC 5V		
·~PP')	LICE BLIC Dower	<u> </u>			
	USB BUS Power	Power consumption	4.35 W (typ.) (at 5 V input, full pixel)		
Lens mount			C mount		
Lens mount			Lens mount protrusion length of 9 mm or less is supported		
Flange back			17.526, tolerance: 0 mm \sim – 0.05 m		
Optical filter			none		
•			$-5^{\circ} \sim +45^{\circ} /20\% \sim 80\% \text{ (non-condensing)}$		
Verified performance temperature / humidity Storage temperature / humidity			$-25\% + 43\% / 20\% \sim 80\% \text{ (non-condensing)}$ $-25\% \sim + 60\% / 20\% \sim 80\% \text{ (non-condensing)}$		
corage terri	peracure / mannally		•		
Regulations			CE (EN61000-6-2 and EN61000-6-3) 、FCC part 15 class B、		
Regulations	incguiutions		RoHS、WEEE		
Regulations					
	(housin-)		20 v 20 v 41 F - (Western) /		
Regulations Dimensions	(housing)		$29 \times 29 \times 41.5 \text{ mm (W} \times \text{H} \times \text{D)}$ (excluding mount protrutions)		
	(housing)		$29 \times 29 \times 41.5$ mm (W×H×D) (excluding mount protrutions)		

Package contentsCamera

body (1) Sensor protection cap (1) Dear Customer (sheet) (1)

Optional accessories (not supplied)

MP-43 tripod mount

Design and specifications are subject to change without notice.

Approximately 5 minutes of warm-up are required to achieve these specifications.

Caution —

About the verified performance temperature make sure the following temperature conditions are met when operating the unit.

- 1) The camera's internal temperature sensor detects temperatures of 65 °C or less during operation.
- 2) The top surface of the camera's casing is 61 °C or less.

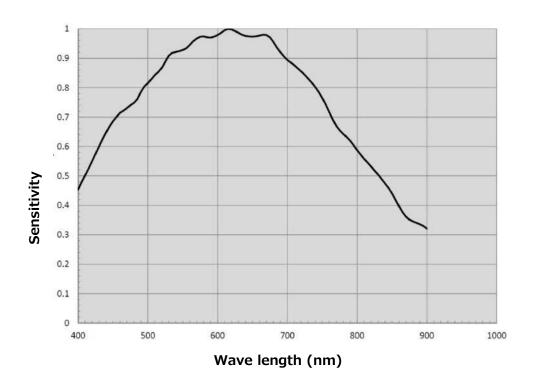
If the above temperature conditions are exceeded, take measures to dissipate heat according to your installation environment and conditions.

Frame Rate Reference

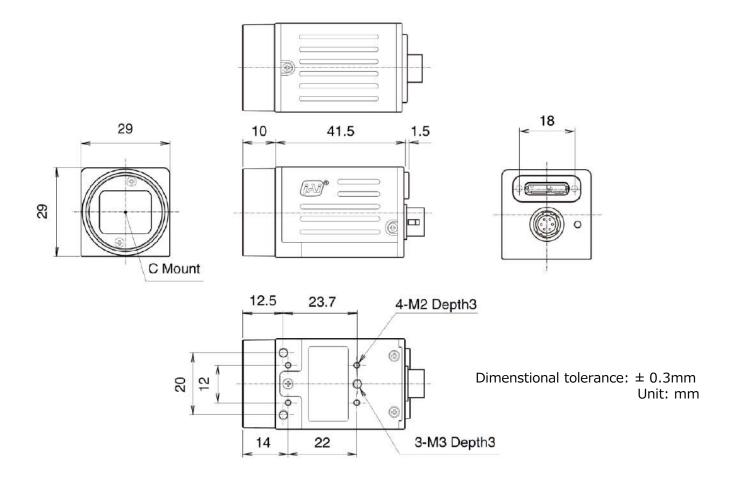
[Theoretical value]

Pixel count	Resolution	Pixel size	Imge size	Frame rate
(MP)	(screen size)	(um)	(mm)	(fps @8bit)
5.1MP	2464 x 2056	3.45 x 3.45	2/3" (11.1 mm)	74.0
2MP	1920 x 1080	3.45 x 3.45	1/2" (7.6 mm)	150.6
1.4MP	1408 x 1050	3.45 x 3.45	1/2.6" (6.04 mm)	154.8
1.3MP	1280 x 1024	3.45 x 3.45	1/2.8" (5.66 mm)	158.6
0.5MP	800 x 600	3.45 x 3.45	1/4.6" (3.45 mm)	263.6
0.3MP	640 x 480	3.45 x 3.45	1/5.75" (2.76 mm)	324.5

Spectral Response



Dimensions



Comparison of the Decibel Display and Multiplier Display

Decibels[db]	Multipliers[x]	Remarks
-6	0.501	
-5	0.562	
-4	0.631	
-3	0.708	
-2	0.794	
-1	0.891	
0	1	
1	1.122	
2	1.259	
3	1.413	
4	1.585	
5	1.778	
6	1.995	
7	2.239	
8	2.512	
9	2.818	
10	3.162	
11	3.548	
12	3.981	
13	4.467	
14	5.012	
15	5.623	
16	6.31	
17	7.079	
18	7.943	
19	8.913	
20	10	
21	11.22	
22	12.589	
23	14.125	
24	15.849	
25	17.783	
26	19.953	
27	22.387	
28	25.119	
29	28.184	
30	31.623	
31	35.481	
32	39.811	
33	44.668	
34	50.119	
35	56.234	
36	63.096	

User's Record

Camera type: GO-5100MP-USB
Revision: ······
Serial No: ······
Firmware version: ······

For camera revision history, please contact your local JAI distributor.

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Revision history

Revision	Date	Changes
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